

Hybrid Unification in the Description Logic \mathcal{EL}

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Outline

- 1 The Description Logic \mathcal{EL} .
- 2 Unification in \mathcal{EL} .
- 3 Hybrid Unification in \mathcal{EL} .
- 4 Hybrid Unification is NP-complete.
- 5 Goal-Oriented Unification Algorithm.
- 6 Conclusions.

The Description Logic \mathcal{EL} . Syntax and Semantics.

\mathcal{EL} concept descriptions

built from finite sets:

$N_C := \{Head_injury, Severe\}$

$N_R := \{status\}$

using concept constructors:

$\top, \sqcap, \exists r.C$

$Head_injury \sqcap \exists status.Severe$

Semantics

An interpretation \mathcal{I} is a pair $(\Delta^{\mathcal{I}}, \cdot^{\mathcal{I}})$ that assigns:

- subsets $C^{\mathcal{I}}$ of $\Delta^{\mathcal{I}}$ to concept names C and,
- binary relations $r^{\mathcal{I}}$ on $\Delta^{\mathcal{I}}$ to role names r .

Semantics of the constructors:

$$\top^{\mathcal{I}} := \Delta^{\mathcal{I}}$$

$$(C \sqcap D)^{\mathcal{I}} := C^{\mathcal{I}} \cap D^{\mathcal{I}}$$

$$(\exists r.C)^{\mathcal{I}} := \{x \mid \exists y : (x, y) \in r^{\mathcal{I}} \wedge y \in C^{\mathcal{I}}\}$$

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The Description Logic \mathcal{EL} . Terminological Axioms.

Concept definitions

$A \equiv C$ for $A \in N_C$ and a concept description C .

A **TBox** \mathcal{T} is a finite set of concept definitions:

$$\left\{ \begin{array}{l} \dots \\ \text{Severe_injury} \equiv \text{Injury} \sqcap \exists \text{status}.\text{Severe} \\ \dots \end{array} \right\}$$

cyclic TBox: $\mathcal{T} = \{A \equiv \dots \sqcap \exists r.B \sqcap \dots, B \equiv \dots \sqcap \exists r.A \sqcap \dots\}$

General Concept Inclusions (GCIs)

$C \sqsubseteq D$ for concept descriptions C, D .

An ontology \mathcal{O} is a finite set of GCIs:

$$\left\{ \begin{array}{l} \dots \\ \text{Severe_injury} \sqsubseteq \text{Injury} \sqcap \exists \text{status}.\text{Severe} \\ \text{Injury} \sqcap \exists \text{status}.\text{Severe} \sqsubseteq \text{Severe_injury} \\ \dots \end{array} \right\}$$

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The Description Logic \mathcal{EL} . Reasoning.

Subsumption problem

$C \sqsubseteq_{\mathcal{O}} D$ iff $C^{\mathcal{I}} \subseteq D^{\mathcal{I}}$ for all models \mathcal{I} of \mathcal{O} .

Equivalence problem

$C \equiv_{\mathcal{O}} D$ iff $C \sqsubseteq_{\mathcal{O}} D$ and $D \sqsubseteq_{\mathcal{O}} C$.

Both problems are polynomial for \mathcal{EL} .

Unification in \mathcal{EL} . Example.

Unification can be used to detect **redundancies** in ontologies.

Two concept descriptions that are meant to represent the concept of a *patient with severe head injury*:

$$Patient \sqcap \exists finding.(Head_injury \sqcap \exists status.Severe)$$
$$Patient \sqcap \exists finding.(Severe_injury \sqcap \exists location.Head)$$

They are not equivalent, but can be made equivalent w.r.t. the following TBox:

$$\left\{ \begin{array}{l} Severe_injury \equiv Injury \sqcap \exists status.Severe \\ Head_injury \equiv Injury \sqcap \exists location.Head \end{array} \right\}$$

Unification in \mathcal{EL} . The decision problem.

Unification problem

N_C is partitioned into a set of defined concepts N_{def} and a set of primitive concepts N_{prim} .

Instance:

An ontology \mathcal{O} .

A finite set of subsumptions $\Gamma = \{C_1 \sqsubseteq^? D_1, \dots, C_n \sqsubseteq^? D_n\}$.

Question:

Is there an **acyclic** TBox \mathcal{T} such that:

$$C_1 \sqsubseteq_{\mathcal{O} \cup \mathcal{T}} D_1, \dots, C_n \sqsubseteq_{\mathcal{O} \cup \mathcal{T}} D_n$$

Observations

\mathcal{O} contains only concept names from N_{prim} .

The solution TBox \mathcal{T} provides definitions for the concept names in N_{def} .

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Unification in \mathcal{EL} . Previous Results.

[Baader and Morawska 2009]

Unification in \mathcal{EL} without background ontology is NP-complete

An \mathcal{EL} -unification problem that is solvable w.r.t. the empty ontology has a solution that is a **local acyclic** TBox.

Locality

Atoms of Γ (At): $C, \exists r.D$ Non-variable atoms (At_{nv}): $At \setminus N_{def}$

A TBox \mathcal{T} is local if each concept definition in \mathcal{T} is of the following form:

$$X \equiv D_1 \sqcap \dots \sqcap D_n$$

where $D_i \in At_{nv}$ for all $i, 1 \leq i \leq n$.

NP-decision procedure

Guesses a local acyclic TBox and then checks whether it is a unifier.

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Extending unification to non-empty ontologies

- The notion of locality does not work.
- Unification problems with solution, but no local unifiers.
- The algorithm is complete only for **cycle restricted** ontologies [Baader, Borgwardt, Morawska 2011].

$$\mathcal{O} \not\models C \sqsubseteq \exists w.C$$

A different approach

Extend what is accepted as a solution to the unification problem:

- Allow the TBox \mathcal{T} to be cyclic.
- Use greatest fixpoint semantics to interpret defined concepts in \mathcal{T} .

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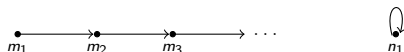
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Hybrid Unification. Greatest fixpoint semantics [Nebel 1991].

Example

- $N_{prim} := \{Node\}$ and $N_{def} := \{INode\}$
- $\mathcal{T} := \{INode \equiv Node \sqcap \exists edge.INode\}$
- \mathcal{J} is an interpretation of $Node$ and $edge$:



- How to extend \mathcal{J} to a model \mathcal{I} of \mathcal{T} ?

classical models: $\{m_1, m_2, \dots\} \cup \{n_1\}$, $\{m_1, m_2, \dots\}$, $\{n_1\}$ or \emptyset .

gfp model: $\{m_1, m_2, \dots\} \cup \{n_1\}$.

Formally,

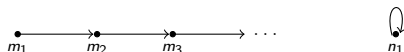
For two extensions $\mathcal{I}_1, \mathcal{I}_2$ of \mathcal{J} : $\mathcal{I}_1 \prec_{\mathcal{J}} \mathcal{I}_2$ iff $X^{\mathcal{I}_1} \subseteq X^{\mathcal{I}_2}$ for each $X \in N_{def}$.

The gfp model is the greatest element of $\prec_{\mathcal{J}}$ that models \mathcal{T} .

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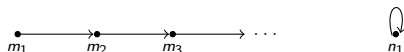
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Hybrid Unification. Hybrid \mathcal{EL} -Ontologies.

Hybrid \mathcal{EL} -ontology [Brandt and Model 2005]

A hybrid \mathcal{EL} -ontology is a pair $(\mathcal{O}, \mathcal{T})$ where \mathcal{O} is an \mathcal{EL} -ontology and \mathcal{T} is a (cyclic) TBox.

An interpretation \mathcal{I} is hybrid model of a hybrid ontology $(\mathcal{O}, \mathcal{T})$ iff:

- \mathcal{I} is an extension of a model \mathcal{J} of \mathcal{O} .
- \mathcal{I} is a gfp model of \mathcal{T} .

Subsumption w.r.t. hybrid ontologies

C is subsumed by D w.r.t. $(\mathcal{O}, \mathcal{T})$ ($C \sqsubseteq_{gfp, \mathcal{O} \cup \mathcal{T}} D$) iff:

$$C^{\mathcal{I}} \subseteq D^{\mathcal{I}}, \text{ for every hybrid model } \mathcal{I} \text{ of } (\mathcal{O}, \mathcal{T})$$

Subsumption is decidable in polynomial time. [Brandt and Model 2005, Novakovic 2007]

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We call such a TBox \mathcal{T} a **hybrid unifier** of Γ w.r.t. \mathcal{O} .

Remark

Acyclic hybrid unifiers are classical unifiers.

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Cyclic hybrid unifiers are **classical** unifiers.

Hybrid Unification. Example.

Ontology

$$\left\{ \begin{array}{l} \text{Human} \sqsubseteq \exists \text{parent.Human} \\ \text{Horse} \sqsubseteq \exists \text{parent.Horse} \end{array} \right\}$$

Unification problem

$$\Gamma := \{ \text{Human} \sqsubseteq^? X, \text{Horse} \sqsubseteq^? X, X \sqsubseteq^? \exists \text{parent.X} \}$$

Γ has a hybrid unifier,

$$\mathcal{T} := \{ X \equiv \exists \text{parent.X} \}$$

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Hybrid Unification is NP-complete. NP-membership.

Proposition

Γ has a hybrid unifier w.r.t. \mathcal{O} iff Γ has a local hybrid unifier w.r.t. \mathcal{O} .

Proof.

Assume that \mathcal{T} is a hybrid unifier of Γ w.r.t. \mathcal{O} . Define \mathcal{S}_X for each $X \in N_{def}$ as:

$$\mathcal{S}_X = \{D \in At_{nv} \mid X \sqsubseteq_{gfp, \mathcal{O} \cup \mathcal{T}} D\}$$

A local TBox \mathcal{T}' is defined as:

$$\mathcal{T}' = \{X \equiv \bigsqcap_{D \in \mathcal{S}_X} D \mid X \in N_{def}\}$$

Show that \mathcal{T}' is also a hybrid unifier of Γ w.r.t. \mathcal{O} . □

Theorem

Hybrid unification w.r.t. to an arbitrary \mathcal{EL} -ontology is in NP.

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\mathcal{EL} -matching problem modulo equivalence

$C \equiv^? D$, where C and D are concept descriptions s.t. C is ground.

Solution

A **substitution** σ such that $C \equiv \sigma(D)$?

Matching in \mathcal{EL} is NP-Complete. [Küster 2001]

Reduction to the hybrid unification problem

Given $C \equiv^? D$, define $\Gamma = \{C \sqsubseteq^? D, D \sqsubseteq^? C\}$ and $\mathcal{O} = \emptyset$.

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$C \equiv^? D$ has a solution iff Γ has a hybrid unifier w.r.t. $\mathcal{O} = \emptyset$.

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Hybrid unification in \mathcal{EL} is NP-hard.

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Proof Calculus **HC** [Novakovic 2007].

A sequent is of the form $C \sqsubseteq_n D$ where C and D are sub-descriptions in $(\mathcal{O}, \mathcal{T})$ and $n \geq 0$.

Rules of **HC**.

$$\begin{array}{c} \frac{}{C \sqsubseteq_n C} \text{ (Ax)} \quad \frac{}{C \sqsubseteq_n \top} \text{ (Top)} \quad \frac{}{C \sqsubseteq_0 D} \text{ (Start)} \\ \\ \frac{C \sqsubseteq_n E}{C \sqcap D \sqsubseteq_n E} \text{ (AndL1)} \quad \frac{D \sqsubseteq_n E}{C \sqcap D \sqsubseteq_n E} \text{ (AndL2)} \quad \frac{C \sqsubseteq_n D \quad C \sqsubseteq_n E}{C \sqsubseteq_n D \sqcap E} \text{ (AndR)} \\ \\ \frac{C \sqsubseteq_n D}{\exists r. C \sqsubseteq_n \exists r. D} \text{ (Ex)} \\ \\ \frac{C \sqsubseteq_n D}{X \sqsubseteq_n D} \text{ (DefL)} \quad \frac{D \sqsubseteq_n C}{D \sqsubseteq_{n+1} X} \text{ (DefR)} \quad \text{for } X \equiv C \in \mathcal{T} \\ \\ \frac{C \sqsubseteq_n E \quad F \sqsubseteq_n D}{C \sqsubseteq_n D} \text{ (GCI)} \quad \text{for } E \sqsubseteq F \in \mathcal{O} \end{array}$$

$C \sqsubseteq_{\text{gfp}, \mathcal{O} \cup \mathcal{T}} D$ iff $C \sqsubseteq_n D$ for all $n \geq 0$ ($C \sqsubseteq_\infty D$).

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Proof Calculus **HC** [Novakovic 2007].

A sequent is of the form $C \sqsubseteq_n D$ where C and D are sub-descriptions in $(\mathcal{O}, \mathcal{T})$ and $n \geq 0$.

Rules of **HC**.

$$\begin{array}{c}
 \frac{}{C \sqsubseteq_n C} \text{ (Ax)} \quad \frac{}{C \sqsubseteq_n \top} \text{ (Top)} \quad \frac{}{C \sqsubseteq_0 D} \text{ (Start)} \\
 \\
 \frac{C \sqsubseteq_n E}{C \sqcap D \sqsubseteq_n E} \text{ (AndL1)} \quad \frac{D \sqsubseteq_n E}{C \sqcap D \sqsubseteq_n E} \text{ (AndL2)} \quad \frac{C \sqsubseteq_n D \quad C \sqsubseteq_n E}{C \sqsubseteq_n D \sqcap E} \text{ (AndR)} \\
 \\
 \frac{C \sqsubseteq_n D}{\exists r. C \sqsubseteq_n \exists r. D} \text{ (Ex)} \\
 \\
 \frac{C \sqsubseteq_n D}{X \sqsubseteq_n D} \text{ (DefL)} \quad \frac{D \sqsubseteq_n C}{D \sqsubseteq_{n+1} X} \text{ (DefR)} \quad \text{for } X \equiv C \in \mathcal{T} \\
 \\
 \frac{C \sqsubseteq_n E \quad F \sqsubseteq_n D}{C \sqsubseteq_n D} \text{ (GCI)} \quad \text{for } E \sqsubseteq F \in \mathcal{O}
 \end{array}$$

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Goal-Oriented Unification Algorithm.

Main idea:

Try to obtain proof trees for $C_i \sqsubseteq_{\ell}^? D_i$ while building \mathcal{T} .

Applies two types of rules:

- *eager* rules (are always applied first) and *nondeterministic* rules.
- rules represent the possible ways to derive $C_i \sqsubseteq_{\ell} D_i$.
- A non-failing application of a rule does the following:
 - it solves exactly one unsolved sequent,
 - it may introduce new proof obligations, i.e.: a sequent $C' \sqsubseteq_{\ell}^? D'$,
 - it may extend the current assignment \mathcal{S} .

Estimation of the value for ℓ ? we need to show $C_i \sqsubseteq_{\infty} D_i$.

- locality \Rightarrow maximal size of \mathcal{T} is bounded w.r.t. the size of \mathcal{O} and Γ .
- ℓ is polynomial on the size of \mathcal{O} and Γ .

Run of the algorithm:

- **Fails:** if a rule application fails or there is an unsolved *sequent* to which no rule applies.
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Goal-Oriented Unification Algorithm. Rules.

Eager Ground Solving:

Applies to ground sequents: $A \sqsubseteq_n^? B \rightarrow$ **fails** if $A \not\sqsubseteq_{\mathcal{O}} B$

Decomposition and Extension:

$$\begin{array}{c} \exists r.X_1 \sqcap \exists r.X_2 \sqsubseteq_n^? \exists r.C \\ \begin{array}{l} \nearrow \\ \searrow \end{array} \\ \begin{array}{l} X_1 \sqsubseteq_n^? C \rightarrow \mathcal{S}_{X_1} = \{C\} \\ X_2 \sqsubseteq_n^? C \rightarrow \mathcal{S}_{X_2} = \{C\} \end{array} \end{array}$$

Mutation (using GCIs):

$$\begin{array}{c} \exists r.X \sqsubseteq_n^? B \\ \begin{array}{l} \swarrow \quad \searrow \\ \exists r.X \sqsubseteq_n^? \exists r.A \quad \mathcal{O} = \{\exists r.A \sqsubseteq B\} \\ B \sqsubseteq_n^? B \end{array} \end{array}$$

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Goal-Oriented Unification Algorithm. Example 1.

$$\mathcal{O} = \{Horse \sqsubseteq \exists parent.Horse, Human \sqsubseteq \exists parent.Human\}$$

$$\Gamma = \{Human \sqsubseteq_{\ell} X, Horse \sqsubseteq_{\ell} X, X \sqsubseteq_{\ell} \exists parent.X\}$$

$$X \sqsubseteq_{\ell} \exists parent.X$$

$$S_X = \emptyset$$

Mutation ($Human \sqsubseteq \exists par \dots$)

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Mutation ($Human \sqsubseteq \exists par \dots$)

$$X \sqsubseteq_{\ell} Human$$

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Extension

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$$Horse \sqsubseteq_{\ell-1} Human$$

Expansion

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Extension

$$Horse \sqsubseteq_{\ell-1} Human$$

Expansion

$$Horse \sqsubseteq_{\ell-1} Human$$

Eager Ground Solving

A failing run, $Horse \not\sqsubseteq_{\mathcal{O}} Human$.

Goal-Oriented Unification Algorithm. Example 2.

$$\mathcal{O} = \{Horse \sqsubseteq \exists parent.Horse, Human \sqsubseteq \exists parent.Human\}$$

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Extension

$$Human \sqsubseteq_{\ell-1} \exists parent.X$$

Expansion

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Extension

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Decomposition

$$Human \sqsubseteq_{\ell-1} X$$

...

$$Human \sqsubseteq_0 X$$

$\mathcal{T} = \{X \equiv \exists parent.X\}$ is a hybrid unifier of Γ w.r.t. \mathcal{O} .

Goal-Oriented Unification Algorithm. Results.

Theorem

*The algorithm is **sound** and **complete**.*

Theorem

*The algorithm is an **NP-decision** procedure for hybrid unification in \mathcal{EL} .*

Conclusions.

Our Results...

- Definition of the hybrid unification problem in \mathcal{EL} w.r.t. arbitrary ontologies.
- Hybrid \mathcal{EL} -unification is NP-complete.
- A sound and complete goal-oriented unification algorithm.

Future Work...

- Implementation of the algorithm. Optimizations (estimation of ℓ ?).
- Decidability and complexity of classical \mathcal{EL} -unification w.r.t. arbitrary ontologies.

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Thanks for your attention!